

QuickGo 2.0

Manage the robot by a cellphone to embrace intelligent robot dispatching.

QuickGo 2.0 is a smart single-vehicle dispatching solution for multi-model robots without traffic management. You can quickly verify a fleet solution, control robot movement, send waybills, and handle daily troubleshooting anytime, anywhere, on multi-device.

5 Single-vehicle Scenarios Without Network 

Connect the robot via a data cable to check the robot's status, and faults, and control the robot's movement directly.

1 Program Trial or Validation Scenarios

Quickly customize a lightweight AGV application to validate the routes, business processes, etc.

2 Complex Scenarios of Loading, Unloading and Transport

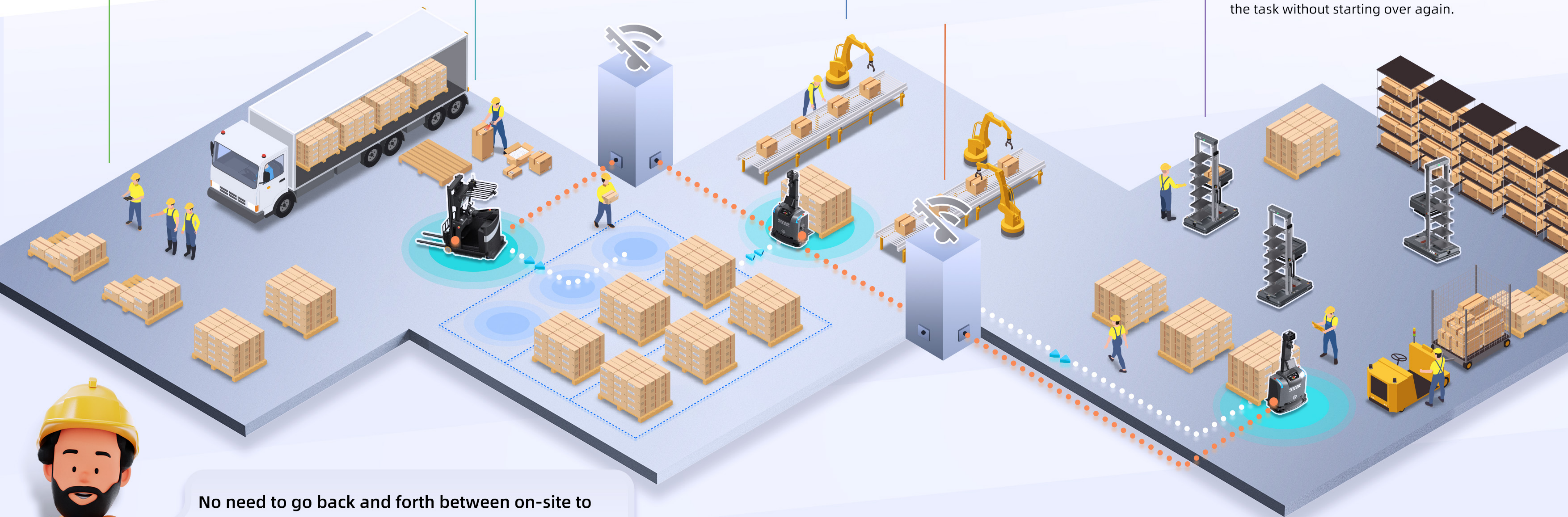
Free switch modes to complete pick-up and drop-off in manual mode and transport cargo automatically by robots.

3 Multi-vehicle Scenarios Without Traffic Control

Realize distribution of the waybill, queuing, canceling, fault recovery, etc. The status of robots is visible in real-time.

4 Carton Transfer Autonomous Robots Scenarios

Switch to manual mode to deal with the failed tasks, change the back tray status, or directly control the forks to transfer the goods, to restart the task without starting over again.



No need to go back and forth between on-site to the office, I can control robots just by my cellphone.



QuickGo 2.0



Directly installed in controller, without additional servers, or industrial controllers, with excellent value for money.



QuickGo has a virtual rocker to provide a smooth game-like vehicle control experience.

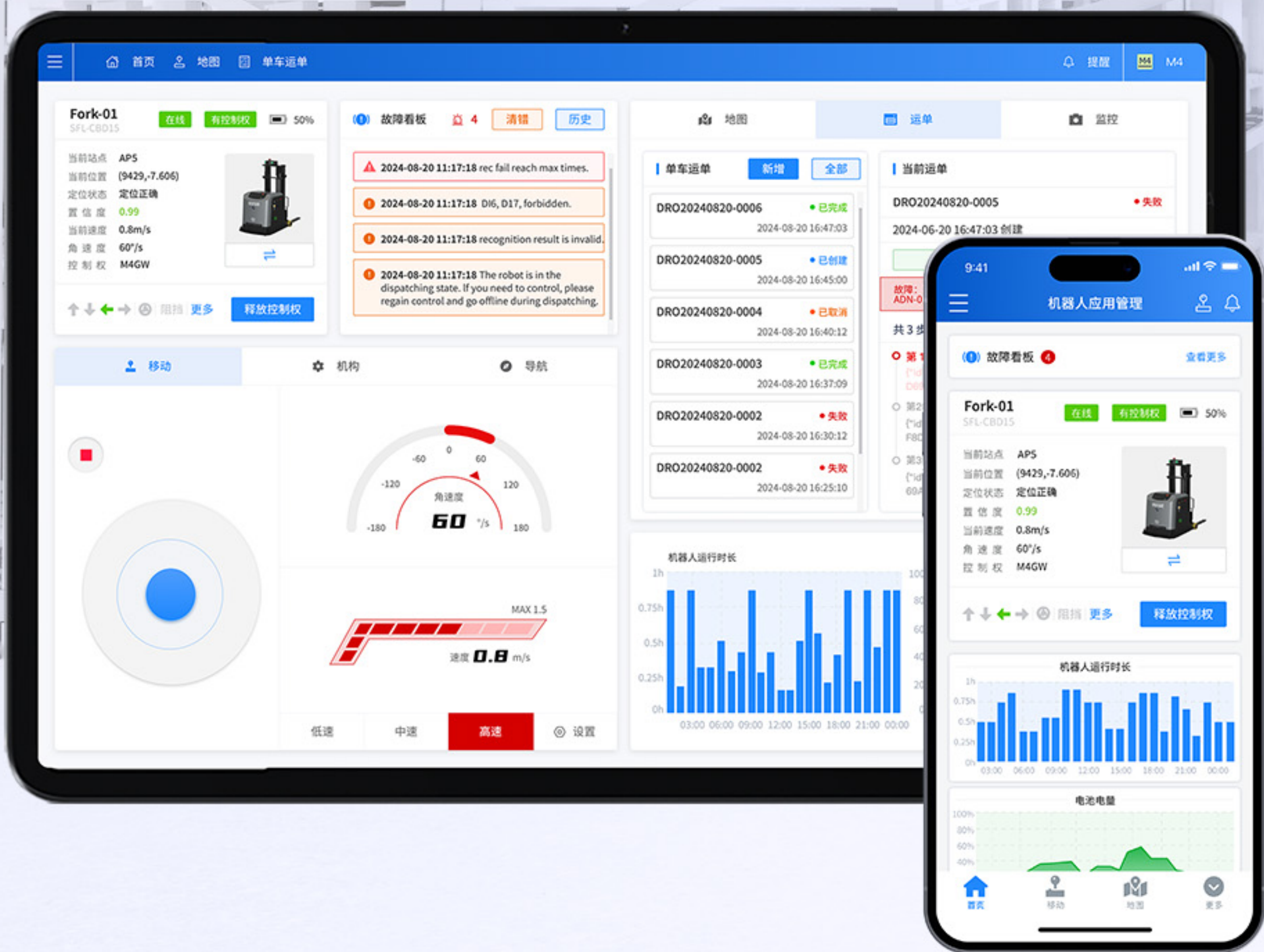


Phones, tablets, and other devices can access QuickGo by scanning the QR code or a data cable.

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AMR Controller



Control Vehicle Directly

Control the open-loop movement of vehicles (forklifts, lifting robot, etc.) and the assembly of robots (forklift fork, lifting, etc.).



Map and Path Navigation

Navigate the robots to a specific point with one-click and real-time updates on navigation progress.



Single-vehicle Falcon Task

Extend more scenarios with a low-code process engine to respond to business process rigidity and change risks.



Unified Interface Management

Provides a friendly interface to check real-time status about robots, waybills, navigation, etc., and manage them uniformly.



Waybill of Single-vehicle

Specify multiple steps in a waybill, and specify a target point and action in each step.



System/Equipment Integration

Interface with upper-level systems, like MES, WMS, WCS, etc., and interact with PLC equipment, such as roller lines, elevators, etc.

Tel: +86-18321029192

E-mail: contact@seer-group.com

Web: www.seer-group.com



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