

Micropulse Transducers

Rod

Rod housings are mainly used in hydraulic drive applications. When installed in the pressure section of the hydraulic cylinder, the displacement sensor requires the same pressure rating as the actual hydraulic cylinder. In practice, the sensor must be able to withstand pressures up to 1000 bar. The electronics are integrated in an aluminum or stainless steel housing and the waveguide in a pressure-resistant tube made from nonmagnetic stainless steel that is sealed off at the front end with a welded plug. An O-ring seal in the flange at the opposite end seals off the high-pressure section. An magnet ring with magnets slides over the tube or rod with internal waveguide to mark the position prior to detection.





BTL7 MICROPULSE +	
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MICROPULSE®



■ www.balluff.com



"long" up to 7620 mm

Pressure-resistant to 600 bar, high reproducibility, contact-less, robust

The Micropulse Transducer BTL is a robust position feedback system for measuring ranges between 25 and 7620 mm as well as for use under extreme ambient conditions.

The actual measurement section is protected inside a high-pressure resistant stainless steel tube. The system is ideal for use in hydraulic cylinders for position feedback or as a level monitor with aggressive media in the food and chemical industries.

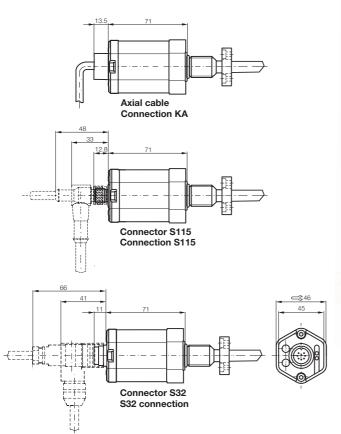
Series	Rod BTL7
Shock load	150 g/6 ms as per EN 60068-2-27
Vibration	20 g, 102000 Hz per EN 60068-2-6
Polarity reversal protected	yes
Overvoltage protected	TransZorb protection diodes
Dielectric strength	500 V AC (GND to housing)
Degree of protection as per IEC 60529	IP 68 with cable outlet, IP 67 with screwed-on plug connector BKS-S
Housing material	Anodized aluminum/1.4571 stainless steel outer tube, 1.3952 stainless steel cast flange
Fasteners	Style B thread M18×1.5, style Z 3/4"-16UNF
Pressure rating	
with 10.2 mm protective tube	600 bar with installation in hydraulic cylinder
with 8 mm protective tube	250 bar installed in hydraulic cylinder
Connection	Connector or cable connection
EMC testing	
Radio interference emission	EN 55016-2-3 (industrial and residential area)
Static electricity (ESD)	EN 61000-4-2 Severity level 3
Electromagnetic fields (RFI)	EN 61000-4-3 Severity level 3
Rapid, transient	IEC 61000-4-4 Severity level 3
electrical pulses (burst)	
Surge voltage	EN 61000-4-5 Severity level 2
Conducted interference induced	EN 61000-4-6 Severity level 3
by high-frequency fields	
Magnetic fields	EN 61000-4-8 Severity level 4

0025...7520 mm in 1 mm increments

Please order separately:

USB communication box, page 146

Standard nominal strokes [mm] with 8 mm outer tube, the max. nominal stroke is 1016 mm





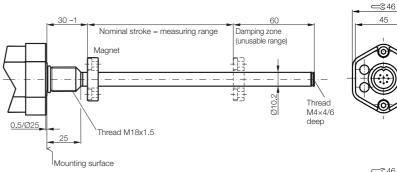
Caution!

Please read the instructions in the user's guide before designing, installing, and commissioning! www.balluff.de



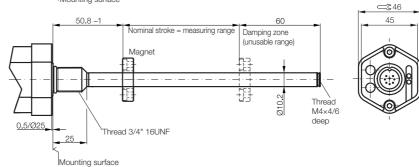
Style B (standard design) BTL7____-B-___

Metric mounting thread M18×1.5



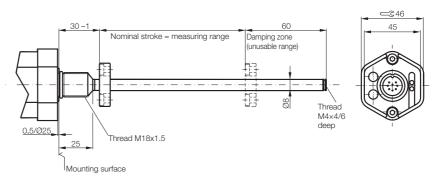
Style Z BTL7___-Z-___

3/4" UNF mounting thread



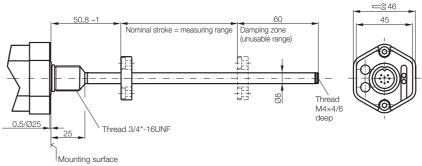
Style B8 BTL7___-B8-___

Metric mounting thread M18×1.5 8 mm protective tube Max. 1016 mm nominal stroke



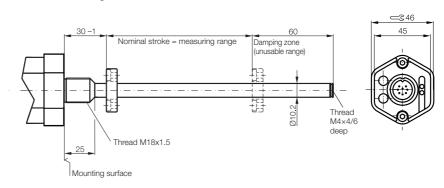
Style Z8 BTL7___-Z8-___

3/4" UNF mounting thread 8 mm protective tube Max. 1016 mm nominal stroke



Style A BTL7-___-A-___

Metric mounting thread M18×1.5 Flange without 0.5/Ø 25 mm mounting surface





Micropulse Transducers

Profile P

Profile PF

Profile AT

Profile BIW

Rod BTL7
General data
Analog interface
Programming

Programming SSI interface Digital pulse interface

Rod BTL5/BTL6
General data
CANopen
interface
Profibus DP
interface
Ethernet
interface
4 programmable
switching points

Float Magnet Installation notices

Rod Compact and Rod AR

Rod EX, T Redundant and CD

Filling Level Sensor SF

Accessories

Basic Information and Definitions



Compatible with BTL5

Features of Micropulse BTL7-A/C/E/G...B, Z, A

- \blacksquare Status LEDs for indicating operating status and diagnostics
- Extended application range due to high degree of protection IP 68 (cable version)
- Electronics head can be replaced in the event of service
- Compact housing, saves space
- Error signal, no magnet within measuring range

Flexible measuring range

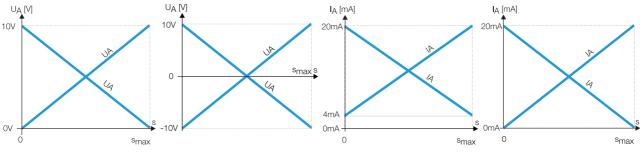
The start and end point of the measuring range can be adapted to the application. The points are set using the included calibration device directly on the unit or remotely, see page 142.

Output signal	
Transducer interface	
Customer device interface	
Part number	
Output voltage	
Output current	
Load current	
Max. residual ripple	
Load resistance	
System resolution	
Hysteresis	
Repeat accuracy	
Sampling rate, length-dependent	
Max. linearity deviation	
Transport of the Control of the Cont	
Temperature coefficient	
Supply voltage	
Current consumption at 24 V DC	
Polarity reversal protected	
Overvoltage protected	
Dielectric strength	
Operating temperature	



Series

Rod BTL7	Rod BTL7	Rod BTL7	Rod BTL7
Analog	Analog	Analog	Analog
Α	G	E	C
Analog	Analog	Analog	Analog
BTL7- A 110-M	BTL7- G 110-M	BTL5- E 1_0-M	BTL7- C 1_0-M
010 V and 100 V	-1010 V and 1010 V		
		420 mA or 204 mA	020 mA or 200 mA
Max. 5 mA	Max. 5 mA		
≤ 5 mV _{pp}	≤ 5 mV _{pp}		
		≤ 500 ohms	≤ 500 ohms
≤ 0.33 mV	≤ 0.33 mV	≤ 0.66 µA	≤ 0.66 µA
≤ 5 µm	≤ 5 µm	≤ 5 µm	≤ 5 µm
System resolution/min. 2 µm	System resolution/min. 2 µm	System resolution/min. 2 µm	System resolution/min. 2 µm
Max. 4 kHz	Max. 4 kHz	Max. 4 kHz	Max. 4 kHz
$\pm 50 \ \mu m$ to $\leq 500 \ mm$ nominal stroke	$\pm 50 \ \mu m$ to $\leq 500 \ mm$ nominal stroke	$\pm 50 \ \mu m \ to \le 500 \ mm \ nominal \ stroke$	$\pm 50 \ \mu m$ to $\leq 500 \ mm$ nominal stroke
±0.01% 5015500 mm nominal stroke	±0.01% 5015500 mm nominal stroke	±0.01% 5015500 mm nominal stroke	±0.01% 5015500 mm nominal stroke
±0.02% FS > 5500 mm nominal stroke	±0.02% FS > 5500 mm nominal stroke	±0.02% FS > 5500 mm nominal stroke	±0.02% FS > 5500 mm nominal stroke
≤ 30 ppm/K	≤ 30 ppm/K	≤ 30 ppm/K	≤ 30 ppm/K
2028 V DC	2028 V DC	2028 V DC	2028 V DC
≤ 150 mA	≤ 150 mA	≤ 150 mA	≤ 150 mA
yes	yes	yes	yes
yes	yes	yes	yes
500 V AC (ground to housing)	500 V AC (ground to housing)	500 V AC (ground to housing)	500 V AC (ground to housing)
−40+85 °C	-40+85 °C	−40+85 °C	−40+85 °C

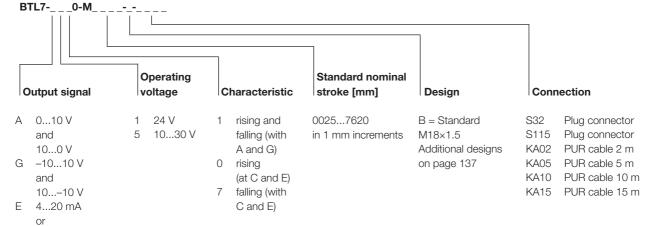


Ordering example:

20...4 mA

0...20 mA or 20...0 mA

С



Micropulse Transducers

Profile P

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Profile BIW

Rod BTL7 General data Analog interface Programming SSI interface Digital pulse interface

Rod BTL5/BTL6 General data CANopen interface Profibus DP interface Ethernet interface 4 programmable switching points

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Accessories

Basic Information and Definitions

www.balluff.com



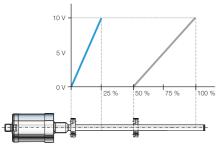
USB configurable

Position and velocity

Two outputs can be assigned any position value and velocity signal using the USB interface.

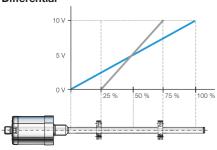
Mode examples:

Double magnet



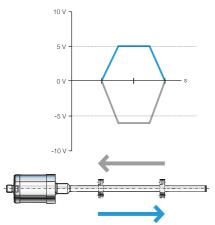
2 magnets, 2 movements, 2 output signals

Differential



Differential signal between 2 magnets, position and difference possible

Velocity



Velocity output

Output signal Transducer interface Position signal interface, customer device Part number Output signal default setting Output signal can be adjusted via Configurable USB Load current Max. residual ripple Load resistance System resolution Current consumption at 24 V DC Hysteresis Repeat accuracy Sampling rate, length-dependent Max. linearity deviation Temperature coefficient Supply voltage Polarity reversal protected Overvoltage protected

Micropulse+ USB configurable BTL7-A/E501

- Simple configuration and adjustment of the start and end point via the USB interface, quick startup
- "Easy Setup" for manual adjustment on-site
- Configurable dual output functions, position and speed
- Increased operating reliability with status LEDs for indicating the operating status and diagnostic information
- Extended application range due to high degree of protection IP 68 (cable version)
- The electronics head can be replaced in the event of service
- Compact housing

Dielectric strength Operating temperature

Series

■ Error signals, no magnet within measuring range

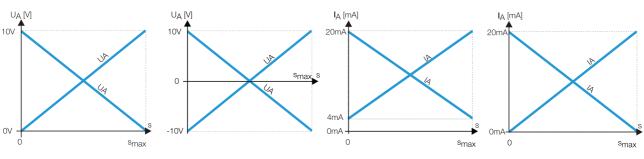
Please enter code for output signal, nominal stroke, design and connection in the part number.

Scope of delivery

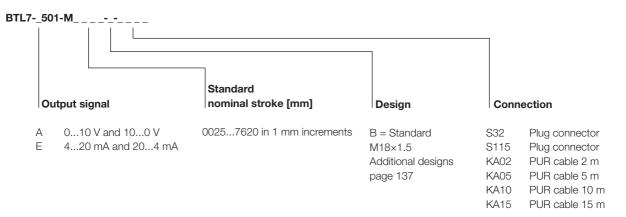
- Transducer
- Calibration device
- Quick start instructions

Please order separately: USB communication box, page 143 Magnets/floats, on page 162 Mounting nuts, on page 163 Plug connectors, page 232

Rod BTL7	Rod BTL7
Analog	Analog
A	E
Analog	Analog
BTL7- A501 -M	BTL7- E501 -M
010 V and 100 V	420 mA and 204 mA
-1010 V and 1010 V	020 mA and 200 mA
Max. 5 mA	
≤ 5 mV _{pp}	
	≤ 500 ohms
≤ 0.33 mV	≤ 0.66 µA
≤ 150 mA	≤ 180 mA
≤ 5 µm	≤ 5 µm
System resolution/min. 2 µm	System resolution/min. 2 µm
Max. 4 kHz	Max. 4 kHz
±50 µm to ≤ 500 mm nominal stroke	±50 µm to ≤ 500 mm nominal stroke
±0.01% FS > 5005500 mm nominal stroke	±0.01% FS > 500≤ 5500 mm nominal stroke
±0.02% FS > 5500 mm nominal stroke	±0.02% FS > 5500 mm nominal stroke
≤ 30 ppm/K	≤ 30 ppm/K
1030 V DC	1030 V DC
yes	yes
yes	yes
500 V AC (ground to housing)	500 V AC (ground to housing)
−40+85 °C	−40+85 °C



Ordering example:



Micropulse Transducers

Profile P

Profile PF

Profile AT

Profile BIW

Rod BTL7 General data

Analog interface

Programming SSI interface Digital pulse interface

Rod BTL5/BTL6 General data CANopen interface Profibus DP interface Ethernet interface 4 programmable switching points

Float Magnet Installation notices

Rod Compact and Rod AR

Rod EX, T Redundant and CD

Filling Level Sensor SF

Accessories

Basic Information and Definitions



Quick commissioning

Setting options for the start and end point

	BTL7 Standard	BTL7-A/E501 Micropulse ⁺ USB configurable
1. Calibration device		
Teach-in		
Adjusting		
Online setting		
Easy Setup		
2. Remote setup		
3. USB configuration		

1. Calibration device

100% start and end point calibration

The start and end points of the analog signal can be set to the optimal position at the touch of a button. Depending on the application, "teach-in" or "adjust" mode is used, and can be selected by pressing a combination of buttons. Two-color LED indicators assist the procedure.

"Easy Setup"

For BTL7-A/E501 Micropulse*only. Simple programming mode for adjusting the start and end point of the transducer to the current application in just a few steps. The magnet is brought into the new position. Confirm by pressing a button. The "Adjust" function allows the new value to be fine-tuned for a stationary magnet. No error value is output during the setup procedure.

Adjusting

Here you can adjust to a new start and end value. This may be required when you cannot physically move the magnet to the start and/or end point. Move the magnet to the new start and end position, and adjust the displayed value by pressing the button until the desired output values are reached.

Online setting

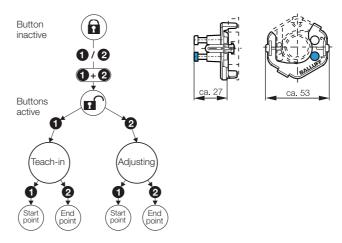
This programming function allows you to set the start and end point while in run mode, such as in a closed loop configuration. No error value is output during the setup procedure. The calibration range is limited to $\pm 25\%$.

Teach-in

The beginning and end points set at the factory are to be replaced by the new beginning and end points.

In addition, the magnet must first be brought into the new beginning position and then into the new end position, and the respective values stored by pressing the button.

Set start and end points using the BTL7-A/EH01 calibration device, included in the scope of delivery.

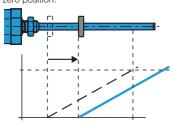


Selecting the calibration procedure BTL7 Standard

Procedure for teach-in, rising signal

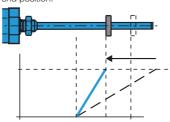
before — — — —

1. Move the magnet into the new zero position.



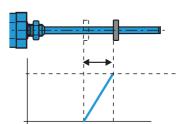
Take over new zero value

2. Move the magnet into the new end position.



Take over new end value

3. Newly set measurement path

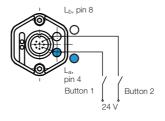




2. Remote setup aid

Remote setting of the start and end points using programming inputs

If the transducer is located in an inaccessible place or a hazardous area, the start and end point can be adjusted remotely. Teach-in, adjustment and online setting are identical to programming with the calibration device. Button 1, blue, corresponds to programming input La and button 2, gray, to input Lb.



3. USB configuration

Start, end value setting and configuration via USB

The Micropulse Configuration Tool software allows the quick and easy configuration of Balluff transducers of type BTL7-A/E501... on a PC.

The most important features are:

- Online display of the current position of the magnet
- Graphical support for setting the functions and characteristics
- Display of information about the connected transducer
- Selectable number formats and units for display
- Reset to factory settings possible
- Calibration device can be disabled
- Demo mode without having a transducer connected

Connecting the USB communication box

For model BTL7-A/E501-M...-S32/S115 transducers, the communication box can be switched between the transducer and the controller. The communication box is connected to the PC using a USB cable.

USB communication box

BTL7-A-CB01-USB-S32,

for BTL7-A/E501... with S32 connector

BTL7-A-CB01-USB-S115,

for BTL7-A/E501... with Connector S115

BTL7-A-CB01-USB-KA,

for BTL7-A/E501... with cable connection

Scope of delivery

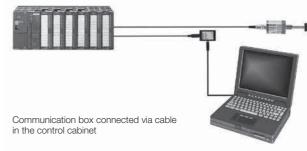
- USB communication box
- Cable set
- Quick start instructions

The PC software and the corresponding manual are available on the Internet at www.balluff.com/downloads-btl7

System requirements

- Standard PC
- Operating system: Windows 2000/XP/Vista/7
- Screen resolution at least 1024 × 768 pixels
- 10 MB available hard disk space
- Install Java Runtime Environment (JRE) Version 1.4.2 or higher http://java.com/getjava
- USB port







Micropulse Transducers

Profile P

Profile PF

Profile AT

Profile BIW

Rod BTL7 General data Analog interface Programming SSI interface

SSI interface Digital pulse interface

Rod BTL5/BTL6
General data
CANopen
interface
Profibus DP
interface
Ethernet
interface
4 programmable
switching points

Magnet Installation notices

Float

Rod Compact and Rod AR

Rod EX, T Redundant and CD

> Filling Level Sensor SF

Accessories

Basic Information and Definitions

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outstanding linear and synchronous performance

SSI interface Micropulse standard for asynchronous operation BTL7-S5_ _-M_ _ _ _-B-_ _ _

Synchronous serial data transmission suitable for controllers from different manufacturers.

Reliable signal transmission, even with cable lengths of up to 400 m between the controller and the BTL transducer, is assured by interruption-free RS485/422 differential drivers and receivers. Any interference signals are effectively suppressed.

SSI interface Micropulse Plus for asynchronous operation BTL7-S510-M____-B-___

Functions, interface parameters and measurement range can be set via an integrated USB interface.

SSI interface Micropulse Standard for synchronous operation BTL7-S5__B-M____-B-___

Micropulse Transducers with synchronized SSI interface are well suited for dynamic control applications. Data acquisition in the transducer is synchronized using the external clock of the controller, allowing an optimum speed calculation to be performed in the regulator/controller.

Prerequisite for this synchronous method of transducer operation is time stability of the clock signal.

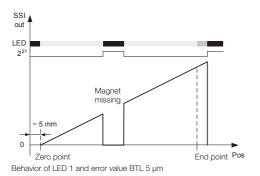
The **maximum sampling frequency** f_A , with which a new, current value is available on each sampling, can be approximated from the set-up. An exact diagram can be found in the current user's guide.

SSI interface Micropulse Plus for synchronous operation BTL7-S510B-M_ _ _ _-B-_ _ _

Via an integrated USB interface, functions, Functions, interface parameters and measurement range can be set via an integrated USB interface.

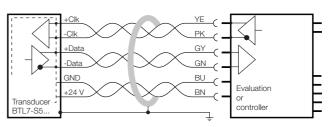
The clock frequency depends on the cable length.

Behavior of LED 1 and the error value over the entire range



LED indicator





BTL7-S5... with evaluation/controller, connection example



Nominal str	oke	area				Scan rate
25 mm	<	Nominal stroke	≤	150 mm	:	4050 Hz
150 mm	<	Nominal stroke	≤	300 mm	:	3250 Hz
300 mm	<	Nominal stroke	≤	500 mm	:	2200 Hz
500 mm	<	Nominal stroke	≤	1000 mm	:	1200 Hz
1000 mm	<	Nominal stroke	≤	2000 mm	:	650 Hz
2000 mm	<	Nominal stroke	≤	7620 mm	:	170 Hz

Cable length	Clock frequency
< 20 m	< 1000 kHz
< 50 m	< 600 kHz
< 100 m	< 330 kHz
< 200 m	< 180 kHz
< 400 m	< 90 kHz

LED 1	
Green	Normal function
	The magnet is within the limits
Red	Error
	No magnet, or magnet is outside the limits

LED 2	
Green	Synchronous operation
	Internal measurement is synchronous with SSI query
Off	Asynchronous operation
	Internal measurement is asynchronous with SSI query
Red	SSI communication error
	T ₀ or T _m event has occurred
Flashing	Programming mode
areen	Only with BTL7-S510(B)





Series	Rod BTL7
Output signal	Synchronous-serial
Transducer interface	S
Customer device interface	Synchronous-serial Synchronous-serial
Part number - Standard asynchronous	BTL7-S5M
Part number - Plus asynchronous	BTL7-S510-M
Part number - Standard synchronous	BTL7-S5_ B -M
Part number - Plus synchronous	BTL7-S510 B -M
System resolution depending on model (LSB)	1, 2, 5, 10, 20, 40, 50 or 100 µm
Repeat accuracy	≤ 11 µm, typical ±2 µm
Hysteresis	≤7 µm
Max. linearity deviation	±30 µm with 5 and 10 µm resolution or ≤ ±2 LSB
Temperature coefficient, typical	≤ 15 ppm/K
Operating voltage, stabilized	1030 V DC
Current consumption	≤ 120 mA
Operating temperature	−40+85 °C
Storage temperature	−40+100 °C

Micropulse Transducers

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Rod BTL7 General data Analog interface Programming SSI interface

Digital pulse interface

Rod BTL5/BTL6 General data CANopen interface Profibus DP interface

Ethernet interface

4 programmable switching points

Float Magnet Installation notices

Rod Compact and Rod AR

Rod EX, T Redundant

Filling Level Sensor SF

and CD

Accessories

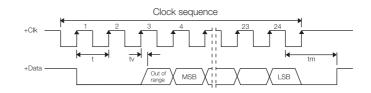
Basic Information and Definitions

Scope of delivery

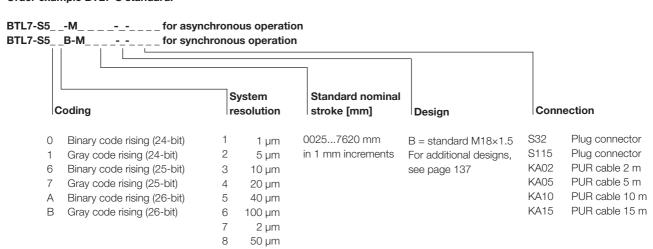
■ Transducer

■ Quick start instructions

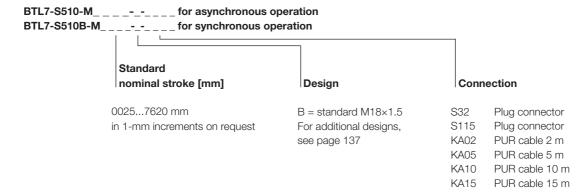
Please enter code for coding, system resolution, nominal stroke, design and connection in the part number.



Order example BTL7-S standard:



Order example BTL7-S Plus:



www.balluff.com **BALLUFF** 145

Rod BTL7 Programming

Micropulse Plus BTL7-S510_-... with USB interface Configuration via USB

The BTL7-S510_-... transducers can be configured quickly and easily on a PC.

The most important features are:

- Online display of the current position of the magnet
- Graphical support for setting the functions and characteristics
- Display of information via the connected transducer: model, serial number, firmware version, nominal stroke, SSI output signal
- Selectable number formats and units for display
- Reset to factory settings possible
- Demo mode without having a transducer connected

System requirements

- Standard PC
- Operating system: Windows 2000/XP/Vista/7
- Screen resolution at least 1024 × 768 pixels
- 10 MB available hard disk space
- Install Java Runtime Environment (JRE) Version 1.4.2 or higher http://java.com/getjava
- USB port

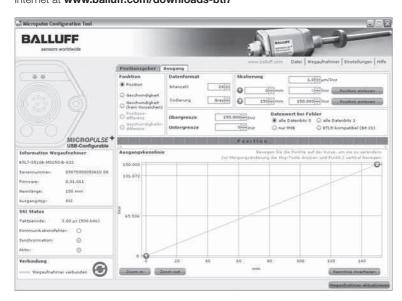
Configuration options of the position measuring system BTL7-S510 $_$ -...

- Number of magnet 1 or 2
- Position
- Velocity
- Differential position
- Speed difference

Interface configuration

- Start/end point
- Rising/falling signal
- Error value
- Data format
- Code
- Resolution

The PC software and the corresponding manual are available on the Internet at www.balluff.com/downloads-btl7





Connecting the USB communication box

With the BTL7-S510-M... transducers, the communication box can be connected between the transducer and controller. The communication box is connected to the PC using a USB cable.

USB communication box BTL7-A-CB01-USB-S32.

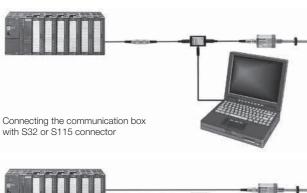
for BTL7-S/510_ ... with S32 connector

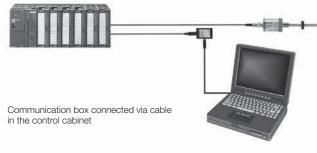
BTL7-A-CB01-USB-S115,

for BTL7-S/510_ ... with S115 connector

BTL7-A-CB01-USB-KA,

for BTL7-S/510_ ... with cable connection





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Profile P

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General data
CANopen
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4 programmable

switching points

Rod BTL5/BTL6

Float Magnet Installation notices

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Accessories

Basic Information and Definitions

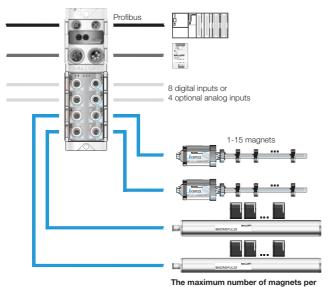


cost-effective + synchronous

Profibus BNI modules are an elegant, cost-effective solution from Balluff.

The modules have a robust metal housing that was designed for use in harsh industrial environments and is capable of withstanding powerful mechanical loads. The modules have four independent ports for Micropulse Transducers BTL with P511. A maximum of 16 magnets can be used per BTL port. The maximum nominal stroke here is 7500 mm. Depending on the version, four additional ports with digital or analog sensors can be assigned. You can achieve maximum functionality and cost efficiency for fieldbus integration by combining Micropulse Transducers BTL with Profibus modules P111.

For more information, see page 244



Highly accurate digitalizations of the P511 pulse signal

Companies developing their own electronic control and evaluation unit can create a highly accurate P interface cost-effectively and with minimum effort using the Balluff digitizing chip. The digitizing chip was developed as a high-resolution, configurable ASIC for Micropulse Transducers with P interface.

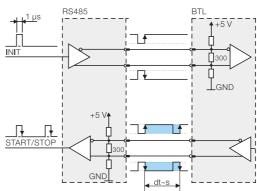
BTL is 16; however altogether, it is 60 per module.

P511 interface – Cost savings using DPI/IP for start-up and installation

DPI/IP is a protocol for direct data interchange between a controller and transducer. The signal lines are used to send additional information such as manufacturer, measuring length and waveguide speed. This allows start-up or replacement of a transducer without having to make manual changes to the controller parameters.

Features

- Bidirectional communication
- Position measuring system controller using Init and start/stop signals
- Integrated diagnostic functions
- Plug and Play
- Automatic configuration reduces downtimes.
- Transmission of sensor type, measuring length, specific parameters
- Measuring length up to 3250 mm



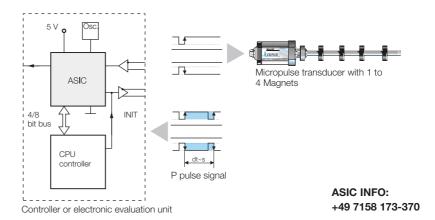
Block diagram of P interface

Advantages:

- High resolution: the actual 1 µm of the BTL position measuring system is supported by the 133 ps resolution of the chip (at low clock frequency 2 or 20 MHz)
- Position data from 4 magnets can be processed simultaneously
- 4/8-bit processor interface



Digitizing chip 44QFP

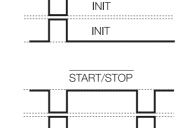




Digital pulse interface

Series	Rod BTL7
Transducer interface	Pulse P511
Customer device interface	Pulse P511
Part number	BTL7- P 511-M
System resolution	processing-dependent
Repeat accuracy	typ. ± 2.5 µm
Hysteresis	≤ ±7 µm
Linearity deviation	±50 µm up to 500 mm nominal stroke
	typ. ±0.01% 5015500 mm nominal stroke
	typ. ±0.02 % 55007620 mm nominal stroke
Ultrasonic speed (standardized)	2850 m/s
Gradient (standardized)	8.9122807 µs/inch
Supply voltage	1030 V
Current consumption at 24 V	120 mA
Operating temperature	−40+85 °C
Storage temperature	-40+100 °C

The rising and falling edges can be evaluated.



START/STOP

Please enter code for nominal stroke, design and connection in the part number.

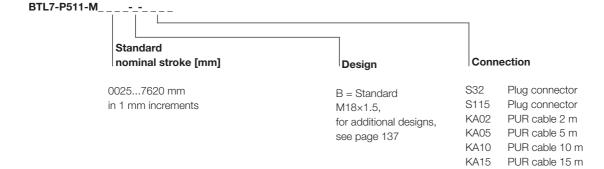
Scope of delivery

■ Transducer

Quick start instructions

Please order separately: Magnets/floats, on page 162 Mounting nuts, on page 163 Plug connector, on page 232

Ordering example:



Micropulse Transducers

Profile P

Profile PF

Profile AT

Profile BIW

Rod BTL7 General data Analog interface Programming SSI interface Digital pulse interface

Rod BTL5/BTL6 General data CANopen interface Profibus DP interface Ethernet interface 4 programmable switching points

Float Magnet Installation notices

Rod Compact and Rod AR

Rod EX, T Redundant and CD

Filling Level Sensor SF

Accessories

Basic Information and Definitions

www.balluff.com **BALLUFF** 149



Pressure-resistant to 600 bar, high reproducibility, contactless, robust

The BTL Micropulse Transducer is a robust position feedback system for measuring ranges between 25 and 5500 mm as well as for use under extreme ambient conditions.

The actual measurement section is protected inside a high-pressure resistant stainless steel tube.

The system is ideal for use in hydraulic cylinders for position feedback or as a level monitor with aggressive media in the food and chemical industries.

Series	Rod BTL5
Shock load	100 g/6 ms as per IEC 60068-2-27
Vibration	12 g, 102000 Hz per EN 60068-2-6
Polarity reversal protected	yes
Overvoltage protected	TransZorb protection diodes
Dielectric strength	500 V DC (GND to housing)
Degree of protection as per IEC 60529	IP 67 (with IP-67 connector BKS-S attached)
Housing material	Anodized aluminum/1.4571 stainless steel outer tube, 1.3952 stainless steel cast flange
Housing attachment	Style B thread M18×1.5, style Z 3/4"-16UNF
Pressure rating	
at 10.2 mm, protective tube	600 bar with installation in hydraulic cylinder
at 8 mm, protective tube	250 bar when installed in hydraulic cylinder
Connection	Connectors/cables
EMC testing	
Radio interference emission	EN 55016-2-3 (industrial and residential area)
Static electricity (ESD)	EN 61000-4-2 Severity level 3
Electromagnetic fields (RFI)	EN 61000-4-3 Severity level 3
Rapid, transient electrical	IEC 61000-4-4 Severity level 3
pulses (burst)	
Conducted interference induced by	EN 61000-4-6 Severity level 3
high-frequency fields	
Standard nominal strokes [mm]	00255500 mm in 1 mm increments,

Scope of delivery

■ Transducer (select your interface from page 152)

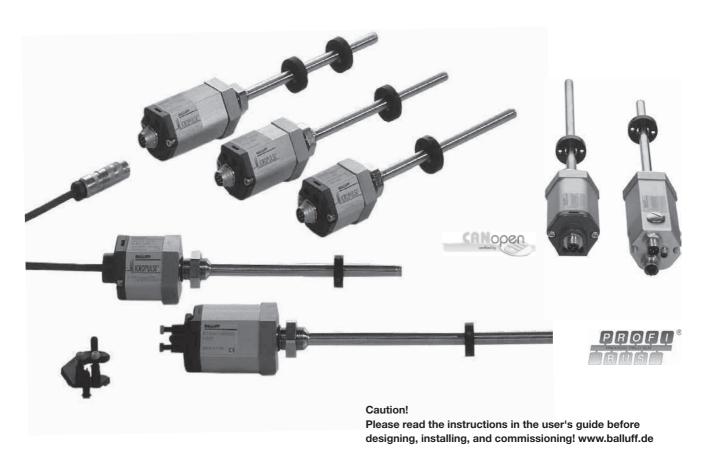
with an 8 mm outer tube, the

max. nominal stroke is 1016 mm

Quick start instructions

Please order separately: Magnets/floats, on page 162 Mounting nuts, on page 163 Plug connectors, page 232

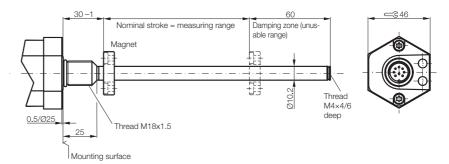
depending on the interface





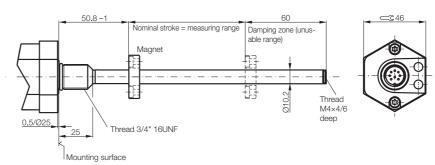
Style B (standard design) BTL5____-B-___

Metric mounting thread M18×1.5



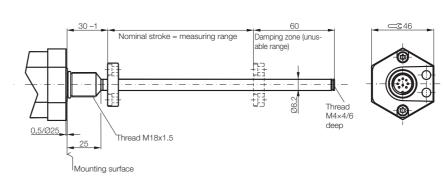
Style Z BTL5____-Z-___

3/4" UNF mounting thread



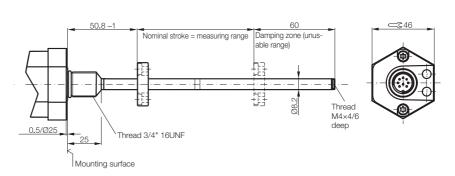
Style B8 BTL5____-B8-___

Metric mounting thread M18×1.5 8 mm protective tube Max. 1016 mm nominal stroke



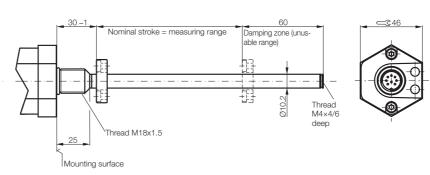
Style Z8 BTL5____-Z8-___

3/4"-UNF mounting thread 8 mm protective tube Max. 1016 mm nominal stroke



Style A BTL5-___-A-___

Metric mounting thread M18×1.5 Flange without 0.5/Ø 25 mm mounting surface



Micropulse Transducers

Profile P

Profile PF

Profile AT

Profile BIW

Rod BTL7 General data Analog interface Programming SSI interface Digital pulse interface

Rod BTL5/BTL6

General data CANopen interface Profibus DP interface Ethernet interface 4 programmable switching points

Float Magnet Installation notices

Rod Compact and Rod AR

Rod EX, T Redundant and CD

Filling Level Sensor SF

Accessories

Basic Information and Definitions

www.balluff.com **BALLUFF**



Position + velocity

CANopen interface

Based on CAN (ISO/IEC 7498 and DIN ISO 11898), CANopen provides a Layer-7 implementation for industrial CAN networks. The serial data protocol of the CAN specification is defined according to the producer-consumer principle as opposed to most other fieldbus protocols. This eliminates target addressing of the process data. Each bus node decides for itself how the received data is processed. The CANopen interface of the Micropulse Transducer is compatible with CANopen conforming with CiA Standard DS301 Rev. 3.0, and with CAL and Layer 2 CAN networks.

EDS

CANopen offers a high level of flexibility in configuring functionality and data exchange. Using a standard data sheet in the form of an EDS file, it is easy to link the Micropulse Transducers to any CANopen system.

Process Data Object (PDO)

Micropulse Transducers send their measured values optionally in one, two or four PDOs with 8 bytes of data each. The contents of the PDOs are freely configurable. The following information can be sent:

- The current magnet with a resolution in 5 µm increments
- the current speed of the magnet, with resolution selectable in 0.1mm/s increments
- the current status of four freely programmable cams per Magnet

Synchronization Object (SYNC)

Serves as a network-wide trigger for synchronizing all network nodes. When the SYNC object is received, all Micropulse Transducers connected to the CANopen bus store their current position and speed information, and then send it sequentially to the controller. This assures time-synchronous detection of the measured values.

I FD

Display of the CANopen status to DS303-3

FMM

The sensor can be operated as a 4-magnet type, whereby the sensor itself recognizes how many magnets are currently active. So if only two magnets are positioned in the measuring range, a valid value is output for the first two positions, and a defined error value in positions 3 and 4.

Emergency Object

This object is sent with the highest priority and is used, for example, for high-priority transmission of error messages when the cam states change.

Service Data Object (SDO)

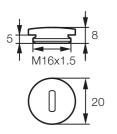
Service data objects transmit the parameters for the configuration to the transducer. The transducer may be configured on the bus by the controller or offline with a bus analyzer/CAN open tool. The configuration is stored in the non-volatile memory of the transducer.



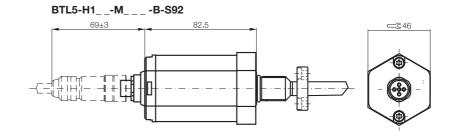
CiA 199911-301v30/11-009

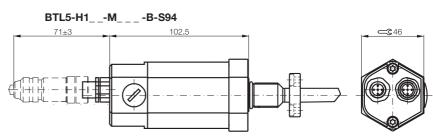
Use of multiple Magnets

The minimum distance between the magnets must be $65\ \mathrm{mm}.$



Transparent cover **BKS 16-CS-00** Ordering code: **BAM0116**





Node ID can be set by DIP switch.

Series		BTL5 rd	d								
Output signal		CANope	en								
Transducer interface		Н									
Customer device inte	rface	CANope	en								
Part number		BTL5-H	1M	S92							
Part number		BTL5-H	1M	S94							
Repeat accuracy		±1 digit									
System resolution	Position	5 µm inc	rements								
Configurable	0.1 mm/	0.1 mm/s increments									
Hysteresis		≤ 1 digit									
Sampling rate		f _{STANDARI}	$_{0} = 1 \text{ kHz}$							Micropulse Transducers	
Max. linearity deviatio	Max. linearity deviation		±30 µm at 5 µm resolution								
Temperature coefficier	nt of overall system	$(6 \mu m +$	$(6 \mu m + 5 ppm \times L)/^{\circ}C$								
Supply voltage		2028 \	2028 V DC								
Current consumption	≤ 100 m	≤ 100 mA							Profile PF		
Operating temperatur	-40+8	−40+85 °C							Tromerr		
Storage temperature		-40+1	-40+100 °C						Profile AT		
Cable length [m] per (CiA DS301	< 25	< 50	< 100	< 250	< 500	< 1000	< 1250	< 2500		
Baud rate [kbaud] per	r CiA DS301	1000	800	500	250	125	100	50	20/10	Profile BIW	

Bit-Stuffing RTR-Bit (Remote-Transmission-Request) Delimiting Bits dominan 11 6 0...8 Byte 15 3 Number of Bits Data Field End-of-Start-of-Identifier ACK Slo Intermission Control Field Message Bit Arbitration Field CRC-Field Acknowledge-Field Data Frame

Data Frame

Using the CANopen interface and a cable up to 2500 m in length, the signal is sent at a length-dependent baud rate to the controller. The high interference immunity of the connection is achieved using differential drivers and by the data monitoring scheme.

Please enter code for software configuration, baud rate and nominal stroke in the part number. Cable on request.

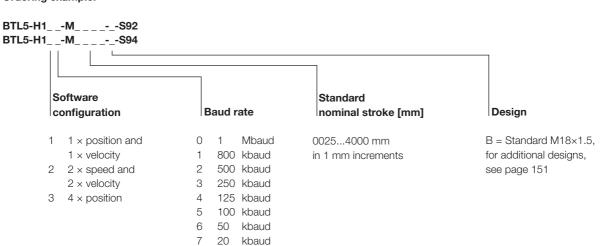
Scope of delivery

■ Transducer

Quick start instructions

Please order separately: Magnets/floats, on page 162 Mounting nuts, on page 163 Plug connectors, page 232

Ordering example:



8 10

kbaud

Rod BTL7 General data Analog interface Programming SSI interface Digital pulse interface

Rod BTL5/BTL6 General data

CANopen interface

Profibus DP interface Ethernet interface

4 programmable switching points

Floats Magnet Installation notices

Rod Compact and Rod AR

Rod EX, T Redundant and CD

Filling Level Sensor SF

Accessories

Basic Information and Definitions

■ www.balluff.com BALLUFF 153



CANopen® + 2 analog inputs

Connecting analog sensors

BTL5-H1A/C/E _ -M _ _ _ -A/B/Y/Z(8)-C001 allows the use of analog pressure or temperature sensors in parallel with the transducer. In this manner, the measured values of the analog sensors are transferred very easily in the CAN protocol.

Analog inputs are detected in series, not simultaneously. The second channel is converted while the first channel is being read and vice versa

The analog process signal from the BTL is converted into digital form because the analog values from the BTL are only processed in digital form. The overall conversion time consists of the time the converter takes to perform the conversion plus additional processing time in the microcontroller (μ C).

The analog values are displayed in the form of a fixed-point number in the 2's complement. The prefix of the analog value is always in bit 15.

■ "0" for +

■ "1" for -

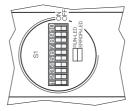


Use of one to four Magnets

The number of magnets can be preset to 1-4 via CANopen. The transducer is preset to operate with an magnet on delivery. The minimum distance between the magnets must be 65 mm.

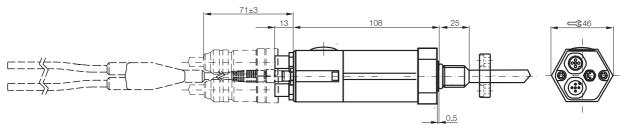
Setting the node ID

For the node ID, values between 0 to 63 can be preset using DIP switches \$1.1...\$1.6.

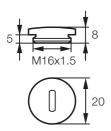


Top view of DIP switch S1

BTL5-H1__-M___--C001



The Node ID can be set by DIP switch.



Transparent cover **BKS 16-CS-00** Ordering code: **BAM0116**

Series		Rod BT	L5							
Output signal		CANope	CANopen							
Transducer interface		Н	H							
Customer device inte	Customer device interface		CANopen							
Part number		BTL5-H	1M							
CANopen version		Potentia	ll-free							
Repeat accuracy		±1 digit								
System resolution Position		5 µm ind	5 µm increments							
Configurable	Velocity	0.1 mm	s increment	ts						
Hysteresis		≤ 1 digit	≤ 1 digit							
Sampling rate		f _{STANDAR}	$f_{STANDARD} = 1 \text{ kHz}$							
Max. linearity deviation	on	±30 µm	±30 µm at 5 µm resolution							
Temperature coefficie	nt of overall system	$(6 \mu m +$	$(6 \mu m + 5 ppm \times L)/^{\circ}C$							
Supply voltage		2028	2028 V DC							
Current consumption		≤ 100 m	≤ 100 mA							
Operating temperature		-40+8	-40+85 °C							
3		-40+1	00 °C							
		< 25	< 50	< 100	< 250	< 500	< 1000	< 1250	< 2500	
Baud rate [kbaud] per CiA DS301			800	500	250	125	100	50	20/10	

Bit-Stuffing Delimiting Bits RTR-Bit (Remote-Transmission-Request) dominan 11 6 0...8 Byte 15 3 Number of Bits Data Field End-of-Start-of-Identifier ACK Slo Intermission Control Field Message Bit Arbitration Field CRC-Field Acknowledge-Field Data Frame

Using the CANopen interface and a cable up to 2500 m in length, the signal is sent at a length-dependent baud rate to the controller. The high interference immunity of the connection is achieved using differential drivers and by the data monitoring implemented in the data protocol.

Please enter code for input configuration, baud rate and nominal stroke in the part number. Cable on request.

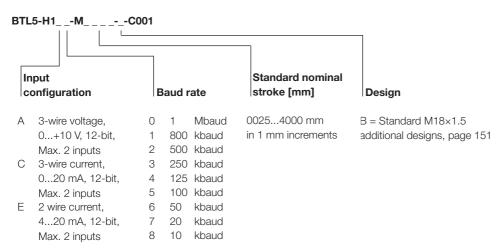
Scope of delivery

■ Transducer

Quick start instructions

Please order separately: Magnets/floats, on page 162 Mounting thread nut, on page 163 Plug connector, on page 232

Ordering example:



Rod BTL7 General data Analog interface Programming SSI interface Digital pulse interface

Profile BIW

Micropulse Transducers

Profile P
Profile PF
Profile AT

Rod BTL5/BTL6 General data

CANopen interface

Profibus DP interface Ethernet interface

4 programmable switching points

Float Magnet Installation notices

Rod Compact and Rod AR

Rod EX, T Redundant and CD

Filling Level Sensor SF

Accessories

Basic Information and Definitions

■ www.balluff.com BALLUFF | 155



Position + Speed

As the market leading standard for serial data transmission for process automation, Profibus DP is the ideal choice for implementing automation tasks with cycle times of $> 5~{\rm ms}$.

Data transmission

A Profibus telegram can contain up to 244 bytes of user data per telegram and node. The BTL5-T uses max. 32 bytes (max. 4 position values and max. 4 speed values) for process data transmission. Up to 126 active stations (Addresses 0 to 125) can be connected on Profibus DP. User data cannot be sent with node address 126. This address is used as the default address for bus nodes that have to be configured by a Class 2 master (for setting the device address if there are no mechanical switches available).

Each Profibus station has the same priority. Prioritizing individual nodes is not intended, but can be done by the master since the bus transmission only makes up a fraction of the process cycle anyway. At a transfer rate of 12 Mbaud, the transmission time for an average data telegram is in the 100 µs range.

GSD (device master data)

The length of the data exchangeable with a slave is defined in the Device Master Data file (GSD) and is checked by the slave with the configuration telegram and confirmed for correctness. In modular systems, various configurations are defined in the GSD file. Depending on the desired functionality, one of these configurations can be selected by the user. The BTL5-T is a modular device with the option of selecting the number of magnets (position values).

Process data

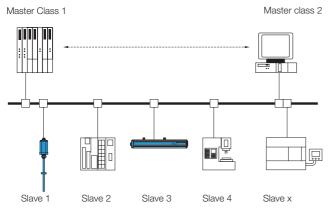
Under Profibus DP, the default is for process data to be sent from the master to slaves acyclically and for the slave data to then be queried. To ensure synchronization of multiple devices, the master may use the SYNC and FREEZE services.

DP/V1 and DP/V2 isochronous mode

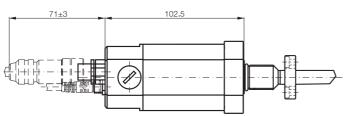
Isochronous mode enables quick and deterministic data exchange by means of clock synchronicity on the bus system. A cyclical, equidistant clock signal is sent by the master to all bus nodes. This signal allows master and slaves to be synchronized irrespective of application – with an accuracy < 1 μs .

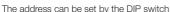
FMM

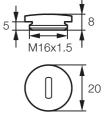
The sensor can be operated as a 4-magnet type, whereby the sensor itself recognizes how many magnets are currently active. This means that if only two magnets are positioned in the measuring range, a valid value is output for the first two positions, and an error value is defined in positions 3 and 4.



The device address can be set by the DIP switch

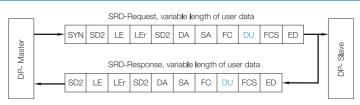






Transparent cover **BKS 16-CS-00** Ordering code: **BAM0116**

Series	Rod BTL5	Rod BTL5								
Output signal	Profibus DP	Profibus DP								
Transducer interface	Т	T								
Customer device interface	Profibus DP	Profibus DP								
Part number plug version S103	BTL5- T 1_0	BTL5- T 1_ 0-MS103								
Profibus version	EN 50170, 6	encoder profile								
Profibus interface	Potential-fre	е								
Repeat accuracy	±1 digit									
System resolution Position	Configurable	e in increments of 5 µm								
Configurable Velocity	0.1 mm/s in	crements configurable								
Hysteresis	≤ 1 digit	≤ 1 digit								
Sampling rate	f _{STANDARD} =	1 kHz								
Max. linearity deviation	±30 µm at 5	±30 µm at 5 µm resolution								
Temperature coefficient of overall system	(6 µm + 5 p)	om × L)/°C								
Magnet travel speed	any	any								
Supply voltage	2028 V D0	0								
Current consumption	≤ 120 mA									
Operating temperature	-40+85 °C									
Storage temperature	-40+100 °	-40+100 °C								
GSD file	BTL504B2.0	BTL504B2.GSD								
Address assignment	Mechanical	switches and Master C	lass 2							
Cable length [m]	< 100	< 200	< 400	<1000	< 1200					
Baud rate [Kbps]	12000	1500	900	187.5	93.7/19.2/9.6					



Please enter code for software configuration, nominal stroke and design in the part number.

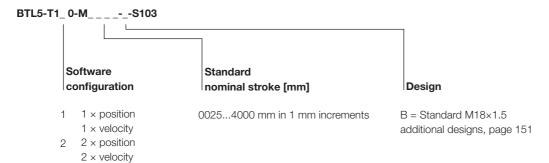
Scope of delivery

■ Transducer

■ Quick start instructions

Please order separately: Magnets/floats, on page 162 Mounting nuts, on page 163 Plug connector, on page 232

Ordering example:



Micropulse
Transducers

Profile P

Profile PF

Profile AT

Profile BIW

Rod BTL7

General data

Analog interface
Programming
SSI interface
Digital pulse
interface

Rod BTL5/BTL6 General data CANopen interface

Profibus DP interface
Ethernet

interface 4 programmable switching points

Float Magnet Installation notices

Rod Compact and Rod AR

Rod EX, T Redundant and CD

Filling Level Sensor SF

Accessories

Basic Information and Definitions

■ www.balluff.com BALLUFF | 157



Real-time Ethernet cost-effective

VARAN feedback system for hydraulically controlled axes

Micropulse position measuring systems with a rod design integrated in the pressure section of the hydraulic cylinder measure the current piston position directly. Optimal control quality of the hydraulic axis is achieved through dynamic, reproducible high-precision measurements. The extremely quick and secure real-time data transmission of the VARAN industrial Ethernet and the precise dynamic measurement of the piston positions of the Micropulse BTL makes the system ideal for use in advanced applications with regulated axes.

Reduction in material and installation costs

The Micropulse position measuring system's single-plug solution lowers total system costs enormously. And every plug connection spared also means that a significant source of errors is eliminated.

Features

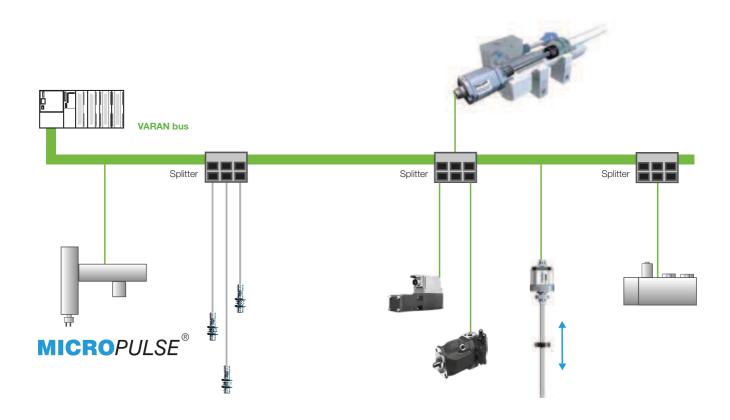
- Non-contact measurement of the measurement position
- Pressure-resistant up to 600 bar (1000 bar) for direct integration in the pressure area
- IP 67, insensitive to contamination
- Insensitive to shock and vibration
- Absolute output signal
- Measurement length up to 4012 mm
- Fast, simple mounting
- Single-plug solution saves system costs

Additional information

For VARAN, see www.varan-bus.net or for EtherCAT, see www.ethercat.org

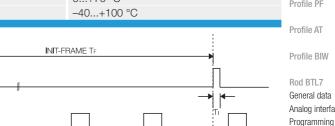






START/STOP

Series	Rod BTL6	Rod BTL6	
Output signal	VARAN	EtherCAT®	
Transducer interface	V11V	V11E	
Customer device interface	VARAN	EtherCAT®	
Part number	BTL6-V11 V -MB-S115	BTL- V 11E-MB-S115	
System resolution	≤ 15 µm	≤ 10 µm	
Repeat accuracy	≤ 20 µm	≤ 30 µm	
Sampling rate	f _{STANDARD} = 1 kHz (< 850 mm)	f _{STANDARD} = 1 kHz (< 850 mm)	
Linearity deviation	≤ ±200 µm up to 500 mm nominal stroke	\leq ±200 µm up to 500 mm nominal stroke	
	±0.04%	±0.04%	
	5001500 mm nominal stroke	5001500 mm nominal stroke	
Supply voltage	2028 V DC	2028 V DC	
Current consumption	≤ 75 mA	≤ 100 mA	
Polarity reversal protected	yes	yes	
Operating temperature	0+70 °C	0+70 °C	
Storage temperature	-40+100 °C	-40+100 °C	



Please enter the code for the nominal stroke in the part number.

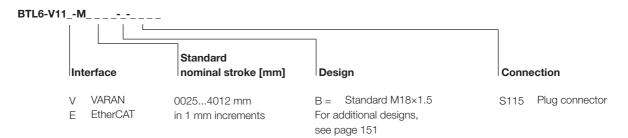
Scope of delivery

■ Transducer

■ Quick start instructions

Please order separately: Magnet/float, page 163 Mounting nuts, on page 163 Plug connector, on page 232

Ordering example:



Micropulse Transducers

Profile P

Profile PF

Analog interface Programming SSI interface Digital pulse interface

Rod BTL5/BTL6 General data CANopen interface Profibus DP interface

Ethernet interface 4 programmable

switching points Float

Installation notices

Magnet

Rod Compact and Rod AR

Rod EX, T Redundant and CD

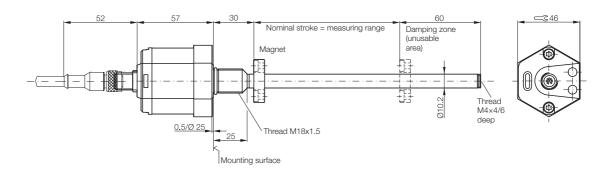
Filling Level Sensor SF

Accessories

Basic Information and Definitions

4 programmable switching points

Rod BTL5



Single position measurement between the piston limits on a standard cylinder series

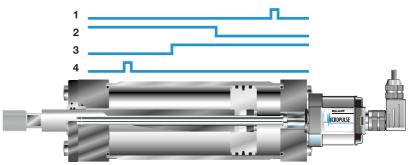
Benefits

- No special design of piston or piston rod necessary
- No permanent magnet required between the piston seals
- Easy to program
- No time-consuming adjustment
- high resolution and reproducibility
- Switching points freely programmable using calibration device or programming inputs

BTL5-A-EH01 calibration device for programming the outputs





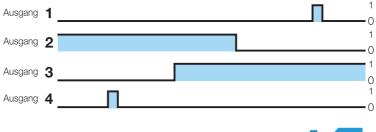






4 programmable switching points

Series	Rod BTL5
Transducer interface	F
Customer device interface	digital
Part number	BTL5- F 1_0-MS115
Output signals	4 switching outputs
Max. current load per output	100 mA
Max. current load for 4 outputs	200 mA
Repeat accuracy	±0.1 mm
Sampling rate	$f_{STANDARD} = 1 \text{ kHz} = \leq 1400 \text{ mm}$
Supply voltage	24 V DC ±20%
Current consumption without load	≤ 100 mA
Operating temperature	−40+85 °C
Storage temperature	-40+100 °C
Shock load	100 g/6 ms as per IEC 60068-2-27
Vibration	12 g, 102000 Hz per EN 60068-2-6
Dielectric strength	500 V DC (GND to housing)
Degree of protection as per IEC 60529	IP 67 (with IP-67 connector BKS-S attached)
Housing material	Anodized aluminum/1.4571 stainless steel outer tube, 1.3952 stainless steel cast flange
Fasteners	Thread M18×1.5, 3/4"-16UNF on request
Pressure rating	600 bar with installation in hydraulic cylinder
Connection	Plug connector



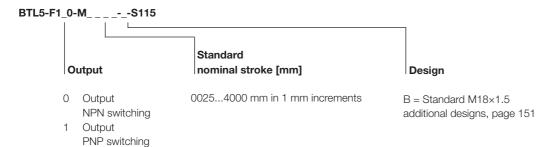
Please enter code for output signal, nominal stroke and design in the part number.

Scope of delivery

- Transducer
- Quick start instructions
- Calibration device

Please order separately: Magnets/floats, on page 162 Mounting nuts, on page 163 Plug connectors, page 232

Ordering example:



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Micropulse Transducers

Profile P

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Rod BTL7 General data Analog interface Programming SSI interface Digital pulse interface

Rod BTL5/BTL6 General data CANopen interface Profibus DP interface Ethernet

interface
4 programmable switching points

Magnet Installation notices

Float

Rod Compact and Rod AR

Rod EX, T Redundant and CD

Filling Level Sensor SF

Accessories

Basic Information and Definitions

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Description	Float	Float	Float	Float	Magnet
					_
for Series	Rod BTL	BTL rod	BTL rod	BTL rod	BTL rod
Ordering code		BAM0146	BAM014C	BAM0149	BAM01CE
Part number	BTL2-S-3212-4Z	BTL2-S-4414-4Z	BTL2-S-6216-8P	BTL2-S-5113-4K	BTL-P-1018-3R
Material	Stainless steel 1.4404	Stainless steel 1.4404	Stainless steel 1.4404	Stainless steel 1.4404	Al
Weight	approx. 20 g	approx. 34 g	approx. 69 g	approx. 35 g	
Magnet travel speed					any
Operating temperature/ Storage temperature	−20+120 °C	-20+120 °C	–20 to +120 °C	-20+120 °C	-40+100 °C
	anness OF mm	annew O1 mm	anness 41 mm	annew 06 mm	
Immersion depth in water	approx. 35 mm	approx. 31 mm	approx. 41 mm	approx. 26 mm	
Pressure resistance (static)	24 bar	20 bar	15 bar	40 bar	
Ordering code					
Part number PA 60					
glass fiber reinforced					
Material					
Weight					
Magnet travel speed					
Operating temperature/ Storage temperature					
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		Ø13 -	Ø16	Ø50.9 Ø13	Ø 54 Ø 28
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	Magnet BTL rod	Magnet BTL rod	Magnet BTL rod	Magnet BTL rod	Magnet BTL rod	Magnet BTL rod
	BAM013Y	BAM013H	BAM013L	BAM013P	BAM013J	BAM013R
	BTL-P-1028-15R	BTL-P-0814-GR-PAF	BTL-P-1013-4R	BTL-P-1013-4S	BTL-P-1012-4R	BTL-P-1014-2R
	Al	Ferrite bound in PA	Aluminum	Aluminum	Aluminum	Aluminum
	approx. 68 g	approx. 1.5 g	approx. 12 g	approx. 12 g	approx. 12 g	approx. 10 g
	any	any	any	any	any	any
	−40+100 °C	−40+100 °C	−40+100 °C	−40+100 °C	-40+100 °C	−40+100 °C
			BAM013M		BAM013K	
			BTL-P-1013-4R-PA		BTL-P-1012-4R-PA	
			PA 60 glass fiber reinforced		PA 60 glass fiber reinforced	
			approx. 10 g		approx. 10 g	
			any		any	
			-40+100 °C		-40+100 °C	
	14		C00			
Ø 28.5 Ø 28.5	120°	Ø17.2 Ø14	032 013	932 13	025	Ø21.9 Ø13.5
	Ø 8		22.5	22.5	18.5	
		0	ω μμ μμ	ω Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.Π.	ω Π Π Π	0
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					4	
	M18×1.5 Mounting nut Order designation: BTL-A-FK01-E-M18×1. Ordering code: BAM01	5 18		9		
	3/4"-16-UNF Mounting Order designation: BTL-A-FK01-E-3/4"-16 Ordering code: BAM01	UNF			ructions in the user's and commissioning!	



Micropulse Transducers

Profile P

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Rod BTL7 General data Analog interface Programming SSI interface Digital pulse interface

Rod BTL5/BTL6 General data CANopen interface Profibus DP interface Ethernet interface 4 programmable switching points

Float Magnet

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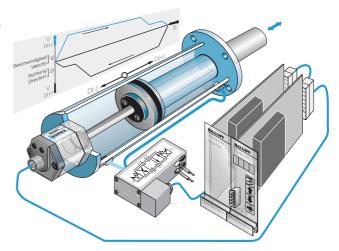
Rod BTL5

Installation notices

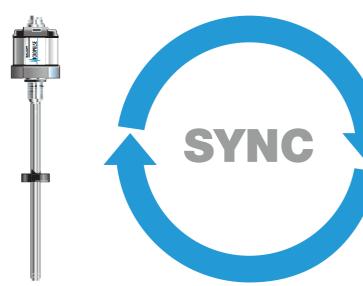
SSI-SYNC - better control behavior and higher dynamics

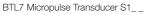
The absolute positioning information from the Micropulse Transducer is transmitted synchronously to the axis control card. This synchronous data acquisition permits a precise calculation of the speed and acceleration.

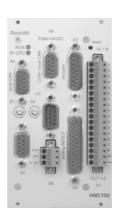
The feedback of these status sizes (speed and acceleration) allows the damping and natural frequency of a hydraulic system to be increased. These measures permit greater loop gain and with it, better control behavior and higher dynamics.



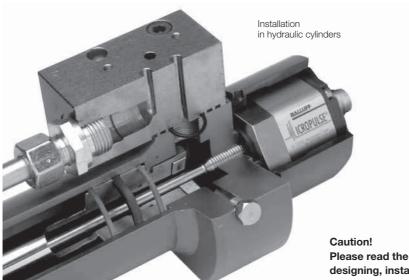
Application with hydraulic cylinder in a control circuit







Control card with SSI interface for connecting Micropulse Transducers



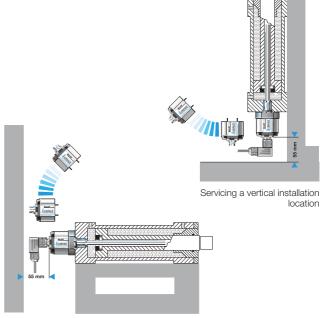
Please read the instructions in the user's guide before designing, installing and commissioning! www.balluff.de



Service without great assembly effort

Transducers are often installed in hydraulic cylinders at locations that are difficult to access. In the event of service, a complete replacement of the electronics with wave guide is often a difficult and expensive proposition.

Should a problem occur in the electronics of the Micropulse Transducer, the electronics head can be easily and quickly exchanged for a new one. The fluid circuit is also not disturbed in the event of service, as no drainage is necessary.



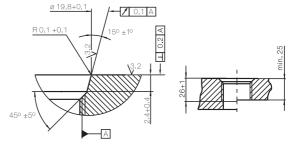
Servicing a horizontal installation location

Installation

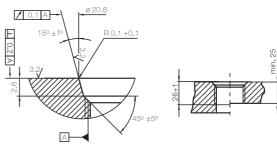
The Micropulse Transducer BTL has a M18×1.5 mounting thread. We recommend that the mounting be made of non-magnetizable material. If magnetizable materials are used, then the measures shown below have to be taken. Sealing is done at the flange mounting surface, for example, in the B design, with a M18×1.5 thread with an included 15.4×2.1 O-ring.

Insertion hole

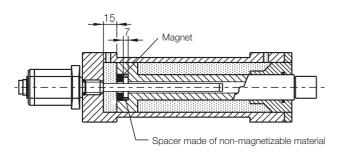
The transducer comes with an M18×1.5 (according to ISO) or a 3/4"-16UNF (according to SAE) thread to secure it. Depending on the version, the threaded hole must be made before installation.

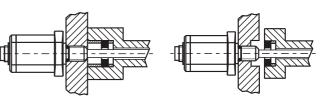


Insertion hole M18×1.5, as per ISO 6149, O-ring 15.4×2.1



Insertion hole 3/4"-16UNF according to SAE J475, 15.3×2.4 O-ring







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